

# UC184xA / 284xA / 384xA

### CURRENT MODE PWM CONTROLLER

THE INFINITE POWER OF INNOVATION

PRODUCTION DATA SHEET

#### **DESCRIPTION**

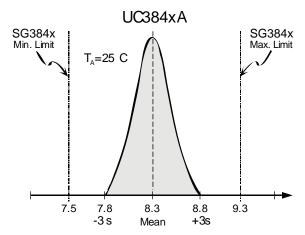
The UC184xA family of control ICs provides externally programmable oscillator to set all the necessary features to implement off-line frequency and maximum duty cycle. The fixed-frequency, current-mode switching power undervoltage lock-out is designed to operate with supplies with a minimum of external components. The current mode architecture bootstrap supply voltage design. Available demonstrates improved load regulation, pulseby-pulse current limiting and inherent protection of the power supply output switch. The IC includes: A bandgap reference trimmed to  $\pm 1\%$ accuracy, an error amplifier, a current sense also available in 14-pin SOIC package which comparator with internal clamp to 1V, a high makes the Power Output Stage Collector and current totem pole output stage for fast Ground pins available. switching of power MOSFET's, and an

250µA typ. start-up current, allowing an efficient options for this family of products, such as startup voltage hysteresis and duty cycle, are summarized below in the Available Options section. The UC184xA family of control ICs is

**IMPORTANT:** For the most current data, consult *MICROSEMI*'s website: http://www.microsemi.com

### PRODUCT HIGHLIGHT

COMPARISON OF UC384xA VS. SG384x DISCHARGECURRENT



Discharge Current Distribution - mA

#### **KEY FEATURES**

- LOW START-UP CURRENT. (0.5mA max.)
- TRIMMED OSCILLATOR DISCHARGE CURRENT. (See Product Highlight)
- **OPTIMIZED FOR OFF-LINE** AND DC-TO-DC CONVERTERS.
- AUTOMATIC FEED FORWARD COMPENSATION.
- PULSE-BY-PULSE CURRENT LIMITING.
- **ENHANCED LOAD RESPONSE** CHARACTERISTICS.
- UNDER-VOLTAGE LOCKOUT WITH HYSTERESIS.
- **DOUBLE PULSE** SUPPRESSION.
- HIGH-CURRENT TOTEM POLE OUTPUT.
- INTERNALLY TRIMMED BANDGAP REFERENCE.
- 500KHz OPERATION.
- LOW RO ERROR AMPLIFIER.

#### **KEY FEATURES**

- **ECONOMICAL OFF-LINE** FLYBACK OR FORWARD CONVERTERS
- DC-DC BUCK OR BOOST CONVERTERS.
- LOW COST DC MOTOR CONTROL.

**Available Options** 

Part#	Start-Up Voltage	Hysteresis	Max. Duty Cycle				
UCx842A	16V	6V	<100%				
UCx843A	8.4V	0.8V	<100%				
UCx844A	16V	6V	<50%				
LICv845A	8 4Δ	0.8\/	<50%				

,	PACKAGE ORDER INFO							
	T <sub>A</sub> (°C)	Plastic DIP 8-Pin	DM Plastic SOIC 8-Pin	Plastic SOIC 14-Pin	Ceramic DIP 8-Pin			
	I <sub>A</sub> (C)	RoHS Compliant / Pb-free Transition DC: 0503	RoHS Compliant / Pb-fr					
Ī	0 to 70	UC384xAM	UC384xADM	UC384xAD	-			
	-40 to +85	UC284xAM	UC284xADm	UC284xAD	UC284xAY			
	-55 to 125	-	-	-	UC184xAY			

Note: Available in Tape & Reel. Append the letters "TR" to the part number. (i.e. UC3842ADM-TR)

#### PRODUCTION DATA SHEET

### 

Note 1. Exceeding these ratings could cause damage to the device. All voltages are with respect to Ground. Currents are positive into, negative out of the specified terminal. Pin numbers refer to DIL packages only.

#### THERMAL DATA

#### M PACKAGE:

MIACIAGE.	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{JA}}$	95°C/W
DM PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{\mathrm{JA}}}$	165°C/W
D PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{\mathrm{JA}}}$	120°C/W
Y PACKAGE:	
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{_{JA}}$	130°C/W

Junction Temperature Calculation:  $T_I = T_A + (P_D \times \theta_{IA})$ .

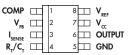
The  $\theta_{JA}$  numbers are guidelines for the thermal performance of the device/pc-board system. All of the above assume no ambient airflow

#### **PACKAGE PIN OUTS**



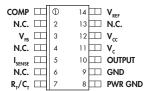
M & Y PACKAGE

(Top View)



DM PACKAGE

(Top View)



**D PACKAGE** 

(Top View)

RoHS / Pb-free 100% Matte Tin Lead Finish



### PRODUCTION DATA SHEET

#### **ELECTRICAL CHARACTERISTICS**

(Unless otherwise specified, these specifications apply over the operating ambient temperatures for UC384xA with  $0^{\circ}$ C  $\leq$   $T_A \leq$  70°C, UC284xA with  $-40^{\circ}$ C  $\leq$   $T_A \leq$  85°C, UC184xA with  $-55^{\circ}$ C  $\leq$   $T_A \leq$  125°C;  $V_{CC}$ =15V;  $V_{CC}$ =15V;  $V_{CC}$ =15V;  $V_{CC}$ =15V;  $V_{CC}$ =10K;  $V_{CC}$ =10K;

Parameter	Symbol	Test Conditions			84xA				Units
raidilletei	Sylliooi	rest conditions	Min.	Тур.	Max.	Min.	Тур.	Max.	Oilit
Reference Section									
Output Voltage	V <sub>REF</sub>	$T_J = 25$ °C, $I_L = 1$ mA	4.95	5.00	5.05	4.90	5.00	5.10	٧
Line Regulation		$12 \le V_{IN} \le 25V$		6	20		6	20	m۷
Load Regulation		1 ≤ I <sub>o</sub> ≤ 20mA		6	25		6	25	m۷
Temperature Stability (Note 2 & 7)				0.2	0.4		0.2	0.4	mV/°
Total Output Variation		Over Line, Load, and Temperature	4.9		5.1	4.82		5.18	٧
Output Noise Voltage (Note 2)	V <sub>N</sub>	$10Hz \le f \le 10kHz, T_{J} = 25^{\circ}C$		50			50		μ۷
Long Term Stability (Note 2)		T <sub>A</sub> = 125°C, t = 1000hrs		5	25		5	25	m\
Output Short Circuit Current	I <sub>sc</sub>		-30	-100	-180	-30	-100	-180	mA
Oscillator Section									
Initial Accuracy (Note 6)		T <sub>1</sub> = 25°C	47	52	57	47	52	57	kH:
Voltage Stability		12 ≤ V <sub>cc</sub> ≤ 25V		0.2	1		0.2	1	%
Temperature Stability (Note 2)		$T_{MIN} \le T_A \le T_{MAX}$		5			5		%
Amplitude (Note 2)		Aut Autor		1.7			1.7		٧
Discharge Current		$T_1 = 25^{\circ}C_1 V_{PIN 4} = 2V$	7.8	8.3	8.8	7.8	8.3	8.8	m∕
-		$V_{PIN,4} = 2V, T_{MIN} \le T_A \le T_{MAX}$	7.5		8.8	7.6		8.8	mA
Error Amp Section		FIRST / WHIS O MOS	'						
Input Voltage		V <sub>PIN 1</sub> = 2.5V	2.45	2.50	2.55	2.42	2.50	2.58	V
Input Bias Current	I <sub>B</sub>	PIN I		-0.3	-1		-0.3	-2	μA
Open Loop Gain	A <sub>VOL</sub>	2 ≤ V <sub>O</sub> ≤ 4V	65	90		65	90		dB
Unity Gain Bandwidth (Note 2)	UGBW	T, = 25°C	0.7	1		0.7	1		МН
Power Supply Rejection Ratio (Note 3)	PSRR	12 ≤ V <sub>CC</sub> ≤ 25V	60	70		60	70		dB
Output Sink Current	IoL	$V_{PIN 2} = 2.7V, V_{PIN 1} = 1.1V$	2	6		2	6		m/
Output Source Current	I <sub>OH</sub>	$V_{PIN 2} = 2.3V, V_{PIN 1} = 5V$	-0.5	-0.8		-0.5	-0.8		mA
Output Voltage High Level	V <sub>OH</sub>	$V_{PIN 2} = 2.3V$ , $R_L = 15K$ to ground	5	6		5	6		٧
Output Voltage Low Level	V <sub>OL</sub>	$V_{\text{PIN }9} = 2.7 \text{V}, R_{\text{L}} = 15 \text{K to } V_{\text{RFF}}$		0.7	1.1		0.7	1.1	٧
Current Sense Section	I OL	PIN 2 / L REF			l	<u> </u>	I		
Gain (Note 3 & 4)	A <sub>VOL</sub>		2.85	3	3.15	2.85	3	3.15	V/V
Maximum Input Signal (Note 3)	VOL	$V_{PIN 1} = 5V$	0.9	1	1.1	0.9	1	1.1	V
Power Supply Rejection Ratio (Note 3)	PSRR	$12 \le V_{CC} \le 25V$		70			70		dB
Input Bias Current	I <sub>B</sub>			-2	-10		-2	-10	μА
Delay to Output (Note 2)	T <sub>pd</sub>	V <sub>PIN 3</sub> = 0 to 2V		150	300		150	300	ns
Output Section	pa	I MN3	I			I			
Output Low Level		I <sub>SINK</sub> = 20mA		0.1	0.4		0.1	0.4	٧
03.04. 2011 2010.	V <sub>OL</sub>	I <sub>SINK</sub> = 200mA		1.5	2.2		1.5	2.2	v
Output High Level		$I_{SOURCE} = 20 \text{mA}$	13	13.5		13	13.5		V
Output High Level	V <sub>OH</sub>	$I_{\text{SOURCE}} = 2011A$ $I_{\text{SOURCE}} = 200\text{mA}$	12	13.5		12	13.5		V
Rise Time (Note 2)	T <sub>R</sub>	$T_1 = 25^{\circ}\text{C}, C_1 = 1\text{nF}$	12	50	150	'-	50	150	ns
· · · · · · · · · · · · · · · · · · ·	- "	, ,		50	150	_	50	150	ns
Fall Time (Note 2)	T <sub>F</sub>	$T_1 = 25^{\circ}C, C_1 = 1nF$		1 50					

(Electrical Characteristics continue next page.)



#### PRODUCTION DATA SHEET

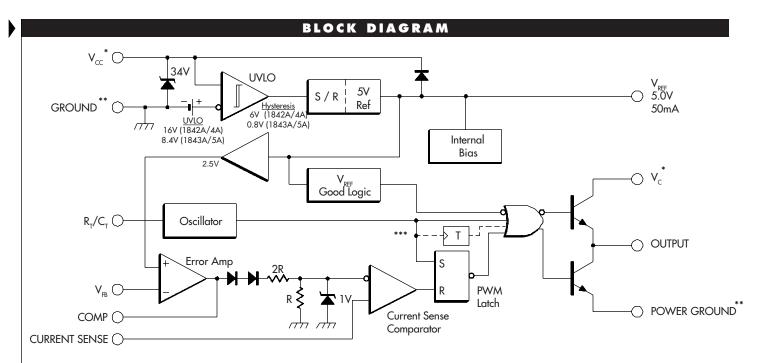
	ELEC'	CTRICAL CHARACTERISTICS (Con't.)										
Parameter	Symbol	Test Conditions		<u> </u>		84xA Max.	_	C384x	Max.	Units		
Under-Voltage Lockout Section			'									
Start Threshold		x842A/4A	1	5	16	17	14.5	16	17.5	٧		
		x843A/5A	7.	8	8.4	9.0	7.8	8.4	9.0	٧		
Min. Operation Voltage After Turn-On		x842A/4A	9	)	10	11	8.5	10	11.5	٧		
		x843A/5A	7.	0	7.6	8.2	7.0	7.6	8.2	٧		
PWM Section			•					•				
Maximum Duty Cycle		x842A/3A	9	4	96	100	94	96	100	%		
		x844A/5A	4	7	48	50	47	48	50	%		
Minimum Duty Cycle						0			0	%		
Total Standby Section			•									
Start-Up Current					0.3	0.5		0.3	0.5	mA		
Operating Supply Current	I <sub>cc</sub>				11	17		11	17	mA		
Zener Voltage	V <sub>z</sub>	$I_{cc} = 25mA$	3	0	35		30	35		٧		

Notes: 2. These parameters, although guaranteed, are not 100% tested in production.

- 3. Parameter measured at trip point of latch with  $V_{VFB} = 0$ .
- $\mbox{4. Gain defined as: } \mbox{$A_{VOL}$} = \frac{\Delta \mbox{$V_{COMP}$}}{\Delta \mbox{$V_{ISENSE}$}} \ \, ; \ \, 0 \leq \mbox{$V_{ISENSE}$} \leq 0.8 \mbox{$V$}. \label{eq:asymptotic_comp}$
- 5. Adjust  $\boldsymbol{V}_{\scriptscriptstyle CC}$  above the start threshold before setting at 15V.
- Output frequency equals oscillator frequency for the UC1842A and UC1843A. Output frequency is one half oscillator frequency for the UC1844A and UC1845A.
- 7. "Temperature stability, sometimes referred to as average temperature coefficient, is described by the equation:

$$Temp \ Stability = \frac{V_{REF} \ (max.) - V_{REF} \ (min.)}{T_{J} \ (max.) - T_{J} \ (min.)}$$

 $\rm V_{\rm REF}$  (max.) &  $\rm V_{\rm REF}$  (min.) are the maximum & minimum reference voltage measured over the appropriate temperature range. Note that the extremes in voltage do not necessarily occur at the extremes in temperature."



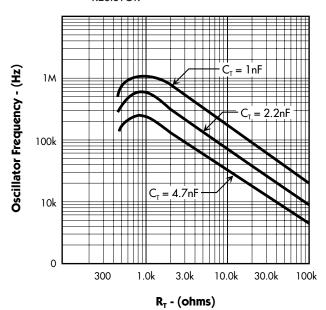
- $\ast$   $\,V_{cc}\,and\,V_{c}$  are internally connected for 8 pin packages.
- \*\* POWER GROUND and GROUND are internally connected for 8 pin packages.
- \*\*\* Toggle flip flop used only in x844A and x845A series.

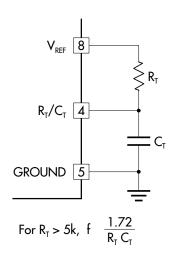


### PRODUCTION DATA SHEET

#### CHARACTERISTIC CURVES

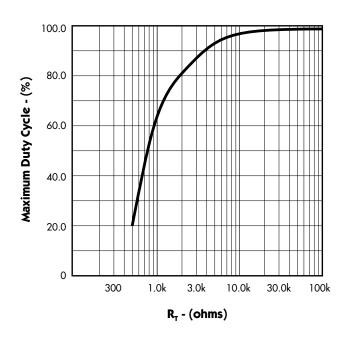
FIGURE 1. — OSCILLATOR FREQUENCY vs. TIMING RESISTOR





Note: Output drive frequency is half the oscillator frequency for the UCx844A/5A devices.

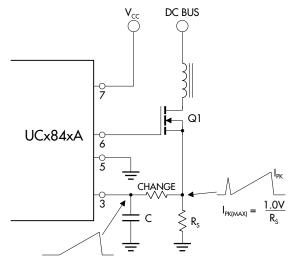
FIGURE 2. — MAXIMUM DUTY CYCLE vs. TIMING RESISTOR



#### PRODUCTION DATA SHEET

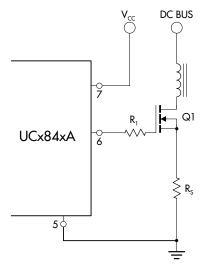
#### TYPICAL APPLICATION CIRCUITS

FIGURE 3. — CURRENT SENSE SPIKE SUPPRESSION



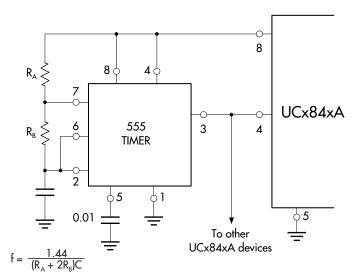
The RC low pass filter will eliminate the leading edge current spike caused by parasitics of Power MOSFET.

FIGURE 4. — MOSFET PARASITIC OSCILLATIONS



A resistor  $(R_1)$  in series with the MOSFET gate will reduce overshoot & ringing caused by the MOSFET input capacitance and any inductance in series with the gate drive. (Note: It is very important to have a low inductance ground path to insure correct operation of the I.C. This can be done by making the ground paths as short and as wide as possible.)

FIGURE 5. — EXTERNAL DUTY CYCLE CLAMP AND MULTI-UNIT SYNCHRONIZATION

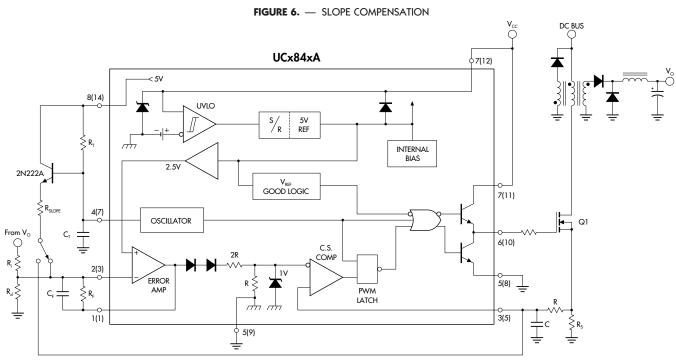


 $f = \frac{R_B}{R_A + 2R_B}$  Precision duty cycle limiting as well as synchronizing several parts is possible with the above circuitry.



#### PRODUCTION DATA SHEET

#### TYPICAL APPLICATION CIRCUITS (continued)



Due to inherent instability of current mode converters running above 50% duty cycle, slope compensation should be added to either the current sense pin or the error amplifier. Figure 6 shows a typical slope compensation technique.

 $\bigvee$   $\bigvee$   $\bigvee$  REF -  $V_{cc}$ UCx84xA 2N2222 4.7K ≤ COMP 100K 1K 2 **ERROR AMP ADJUST** 3 | I<sub>SENSE</sub> OUTPUT 6 OUTPUT ADJUST 4 R<sub>T</sub>C<sub>T</sub> GROUND GROUND

FIGURE 7. — OPEN LOOP LABORATORY FIXTURE

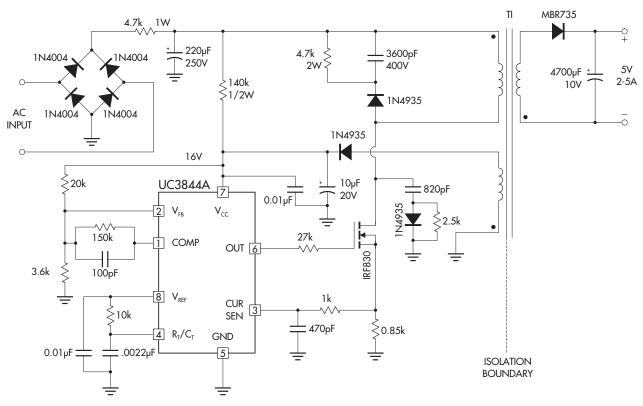
High peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected to pin 5 in a single point ground. The transistor and 5k potentiometer are used to sample the oscillator waveform and apply an adjustable ramp to pin 3.



#### PRODUCTION DATA SHEET

#### TYPICAL APPLICATION CIRCUITS (continued)

FIGURE 8. — OFF-LINE FLYBACK REGULATOR



#### **SPECIFICATIONS**

Input line voltage: 90VAC to 130VAC Input frequency: 50 or 60Hz
Switching frequency: 40KHz ±10%
Output power: 25W maximum
Output voltage: 5V +5%

Output voltage: 5V +5%
Output current: 2 to 5A
Line regulation: 0.01%/V
Load regulation: 8%/A\*

Efficiency @ 25 Watts,

 $V_{IN} = 90VAC:$  70%  $V_{IN} = 130VAC:$  65%

Output short-circuit current: 2.5Amp average

\* This circuit uses a low-cost feedback scheme in which the DC voltage developed from the primary-side control winding is sensed by the UC3844A error amplifier. Load regulation is therefore dependent on the coupling between secondary and control windings, and on transformer leakage inductance.

