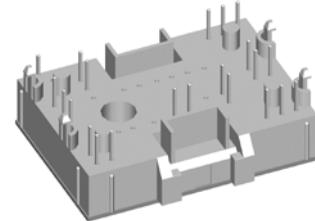
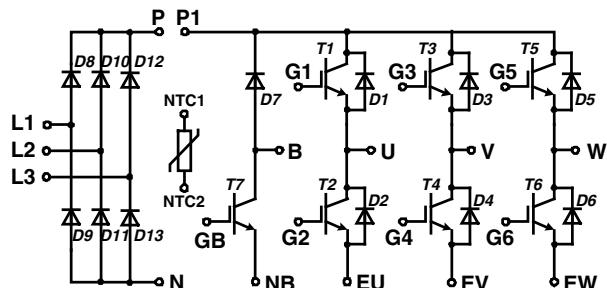


# Converter - Brake - Inverter Module

## Trench IGBT



Pin configuration see outlines.

Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 1200 \text{ V}$	$V_{CES} = 1200 \text{ V}$
$I_{DAVM25} = 90 \text{ A}$	$I_{C25} = 30 \text{ A}$	$I_{C25} = 30 \text{ A}$
$I_{FSM} = 300 \text{ A}$	$V_{CE(sat)} = 1.8 \text{ V}$	$V_{CE(sat)} = 1.8 \text{ V}$

Input Rectifier Bridge D8 - D13			
Symbol	Conditions	Maximum Ratings	
$V_{RRM}$		1600	V
$I_{FAV}$	$T_C = 80^\circ\text{C}$ ; sine 180°	22	A
$I_{DAVM}$	bridge output current; $T_C = 80^\circ\text{C}$ ; rect.; $d = 1/3$	62	A
$I_{FSM}$	$T_{VJ} = 25^\circ\text{C}$ ; $t = 10 \text{ ms}$ ; sine 50 Hz	300	A
$P_{tot}$	$T_C = 25^\circ\text{C}$	50	W

Symbol	Conditions	Characteristic Values			
		( $T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)	min.	typ.	max.
$V_F$	$I_F = 30 \text{ A}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.3 1.4	1.6	V V
$I_R$	$V_R = V_{RRM}$ $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.01 0.3	mA mA	
$R_{thJC}$ $R_{thCH}$	(per diode)		2.1 0.7	K/W K/W	

**Application: AC motor drives with**

- Input from single or three phase grid
- Three phase synchronous or asynchronous motor
- electric braking operation

**Features**

- High level of integration - only one power semiconductor module required for the whole drive
- Inverter with Trench IGBTs
  - low saturation voltage
  - positive temperature coefficient
  - fast switching
  - short tail current
- Epitaxial free wheeling diodes with hiperfast and soft reverse recovery
- Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- Temperature sense included

**Output Inverter T1 - T6**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$V_{GES}$	Continuous	$\pm 20$	V	
$V_{GEM}$	Transient	$\pm 30$	V	
$I_{C25}$	$T_C = 25^\circ\text{C}$	30	A	
$I_{C80}$	$T_C = 80^\circ\text{C}$	21	A	
<b>RBSOA</b>	$V_{GE} = \pm 15\text{ V}$ ; $R_G = 75\text{ }\Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100\text{ }\mu\text{H}$	$I_{CM} = 30$ $V_{CEK} \leq V_{CES}$	A	
<b>t<sub>sc</sub> (SCSOA)</b>	$V_{CE} = 720\text{ V}$ ; $V_{GE} = \pm 15\text{ V}$ ; $R_G = 75\text{ }\Omega$ $T_{VJ} = 125^\circ\text{C}$ ; non-repetitive	10	$\mu\text{s}$	
<b>P<sub>tot</sub></b>	$T_C = 25^\circ\text{C}$	120		W

**Symbol**    **Conditions****Characteristic Values**(T<sub>VJ</sub> = 25°C, unless otherwise specified)

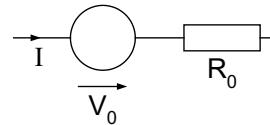
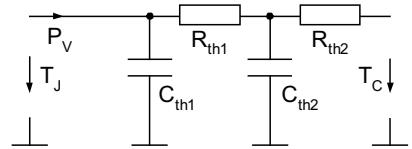
		min.	typ.	max.	
$V_{CE(\text{sat})}$	$I_C = 15\text{ A}$ ; $V_{GE} = 15\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.8 2.1	2.2	V
$V_{GE(\text{th})}$	$I_C = 0.5\text{ mA}$ ; $V_{GE} = V_{CE}$	5		6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.8	0.6	mA
$I_{GES}$	$V_{CE} = 0\text{ V}$ ; $V_{GE} = \pm 20\text{ V}$			150	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600\text{ V}$ ; $I_C = 15\text{ A}$ $V_{GE} = \pm 15\text{ V}$ ; $R_G = 75\text{ }\Omega$		90 50 520 90 2.1 1.5		ns ns ns ns mJ mJ
$C_{ies}$ $Q_{Gon}$	$V_{CE} = 25\text{ V}$ ; $V_{GE} = 0\text{ V}$ ; $f = 1\text{ MHz}$ $V_{CE} = 600\text{ V}$ ; $V_{GE} = 15\text{ V}$ ; $I_C = 15\text{ A}$	1100 150			pF nC
$R_{thJC}$ $R_{thCH}$	(per IGBT)		0.35	1.1	K/W K/W

**Output Inverter D1 - D6**

Symbol	Conditions	Maximum Ratings		
$I_{F25}$	$T_C = 25^\circ\text{C}$	24		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	16		A

**Symbol**    **Conditions****Characteristic Values**

		min.	typ.	max.	
$V_F$	$I_F = 10\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.5	2.4	V
$I_{RM}$ $t_{rr}$	$V_R = 600\text{ V}$ ; $dI_F/dt = -400\text{ A}/\mu\text{s}$ $I_F = 10\text{ A}$ ; $V_{GE} = 0\text{ V}$ ; $T_{VJ} = 125^\circ\text{C}$		16 125		A ns
$R_{thJC}$ $R_{thCH}$	(per diode)		0.55	1.6	K/W K/W

**Equivalent Circuits for Simulation****Conduction****D8 - D13**Rectifier Diode (typ. at T<sub>J</sub> = 125°C)  
 $V_0 = 0.90\text{ V}$ ;  $R_0 = 12\text{ m}\Omega$ **T1 - T6 / D1 - D6**IGBT (typ. at V<sub>GE</sub> = 15 V; T<sub>J</sub> = 125°C)  
 $V_0 = 0.9\text{ V}$ ;  $R_0 = 80\text{ m}\Omega$ Free Wheeling Diode (typ. at T<sub>J</sub> = 125°C)  
 $V_0 = 1.35\text{ V}$ ;  $R_0 = 41\text{ m}\Omega$ **T7 / D7**IGBT (typ. at V<sub>GE</sub> = 15 V; T<sub>J</sub> = 125°C)  
 $V_0 = 0.9\text{ V}$ ;  $R_0 = 80\text{ m}\Omega$ Free Wheeling Diode (typ. at T<sub>J</sub> = 125°C)  
 $V_0 = 1.45\text{ V}$ ;  $R_0 = 63\text{ m}\Omega$ **Thermal Response****D8 - D13**

Rectifier Diode (typ.)

$$C_{th1} = tbd\text{ J/K}; R_{th1} = tbd\text{ K/W}$$

$$C_{th2} = tbd\text{ J/K}; R_{th2} = tbd\text{ K/W}$$

**T1 - T6 / D1 - D6**

IGBT (typ.)

$$C_{th1} = tbd\text{ J/K}; R_{th1} = tbd\text{ K/W}$$

$$C_{th2} = tbd\text{ J/K}; R_{th2} = tbd\text{ K/W}$$

Free Wheeling Diode (typ.)

$$C_{th1} = tbd\text{ J/K}; R_{th1} = tbd\text{ K/W}$$

$$C_{th2} = tbd\text{ J/K}; R_{th2} = tbd\text{ K/W}$$

**Brake Chopper T7**

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$V_{GES}$	Continuous	$\pm 20$		V
$V_{GEM}$	Transient	$\pm 30$		V
$I_{C25}$	$T_C = 25^\circ\text{C}$	30		A
$I_{C80}$	$T_C = 80^\circ\text{C}$	20		A
<b>RBSOA</b>	$V_{GE} = \pm 15 \text{ V}$ ; $R_G = 75 \Omega$ ; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 30$ $V_{CEK} \leq V_{CES}$		A
<b>t<sub>sc</sub> (SCSOA)</b>	$V_{CE} = 720 \text{ V}$ ; $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 75 \Omega$ $T_{VJ} = 125^\circ\text{C}$ ; non-repetitive	10		$\mu\text{s}$
<b>P<sub>tot</sub></b>	$T_C = 25^\circ\text{C}$	120		W

**Symbol Conditions Characteristic Values** $(T_{VJ} = 25^\circ\text{C}$ , unless otherwise specified)

Symbol	Conditions	min.	typ.	max.	
$V_{CE(\text{sat})}$	$I_C = 15 \text{ A}$ ; $V_{GE} = 15 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		1.8 2.1	2.2	V
$V_{GE(\text{th})}$	$I_C = 0.5 \text{ mA}$ ; $V_{GE} = V_{CE}$	5		6.5	V
$I_{CES}$	$V_{CE} = V_{CES}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		0.5	0.5	mA
$I_{GES}$	$V_{CE} = 0 \text{ V}$ ; $V_{GE} = \pm 20 \text{ V}$			150	nA
$t_{d(on)}$ $t_r$ $t_{d(off)}$ $t_f$ $E_{on}$ $E_{off}$	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 600 \text{ V}$ ; $I_C = 15 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$ ; $R_G = 75 \Omega$		90 50 520 90 2.1 1.5		ns ns ns ns mJ mJ
$C_{ies}$ $Q_{Gon}$	$V_{CE} = 25 \text{ V}$ ; $V_{GE} = 0 \text{ V}$ ; $f = 1 \text{ MHz}$ $V_{CE} = 600 \text{ V}$ ; $V_{GE} = 15 \text{ V}$ ; $I_C = 15 \text{ A}$		1100 150		pF nC
$R_{thJC}$ $R_{thCH}$	(per IGBT)		0.35	1.1	K/W K/W

**Brake Chopper D7**

Symbol	Conditions	Maximum Ratings		
$V_{RRM}$	$T_{VJ} = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200		V
$I_{F25}$	$T_C = 25^\circ\text{C}$	15		A
$I_{F80}$	$T_C = 80^\circ\text{C}$	10		A

**Symbol Conditions Characteristic Values**

Symbol	Conditions	min.	typ.	max.	
$V_F$	$I_F = 10 \text{ A}$ ; $V_{GE} = 0 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$		2.0	3.1	V
$I_R$	$V_R = V_{RRM}$		0.2	0.06	mA
$I_{RM}$ $t_{rr}$	$V_R = 600 \text{ V}$ ; $di_F/dt = -400 \text{ A}/\mu\text{s}$ $I_F = 10 \text{ A}$ ; $T_{VJ} = 125^\circ\text{C}$		13 100		A ns
$R_{thJC}$ $R_{thCH}$			0.85	2.5	K/W K/W

IXYS reserves the right to change limits, test conditions and dimensions.

**Temperature Sensor NTC**

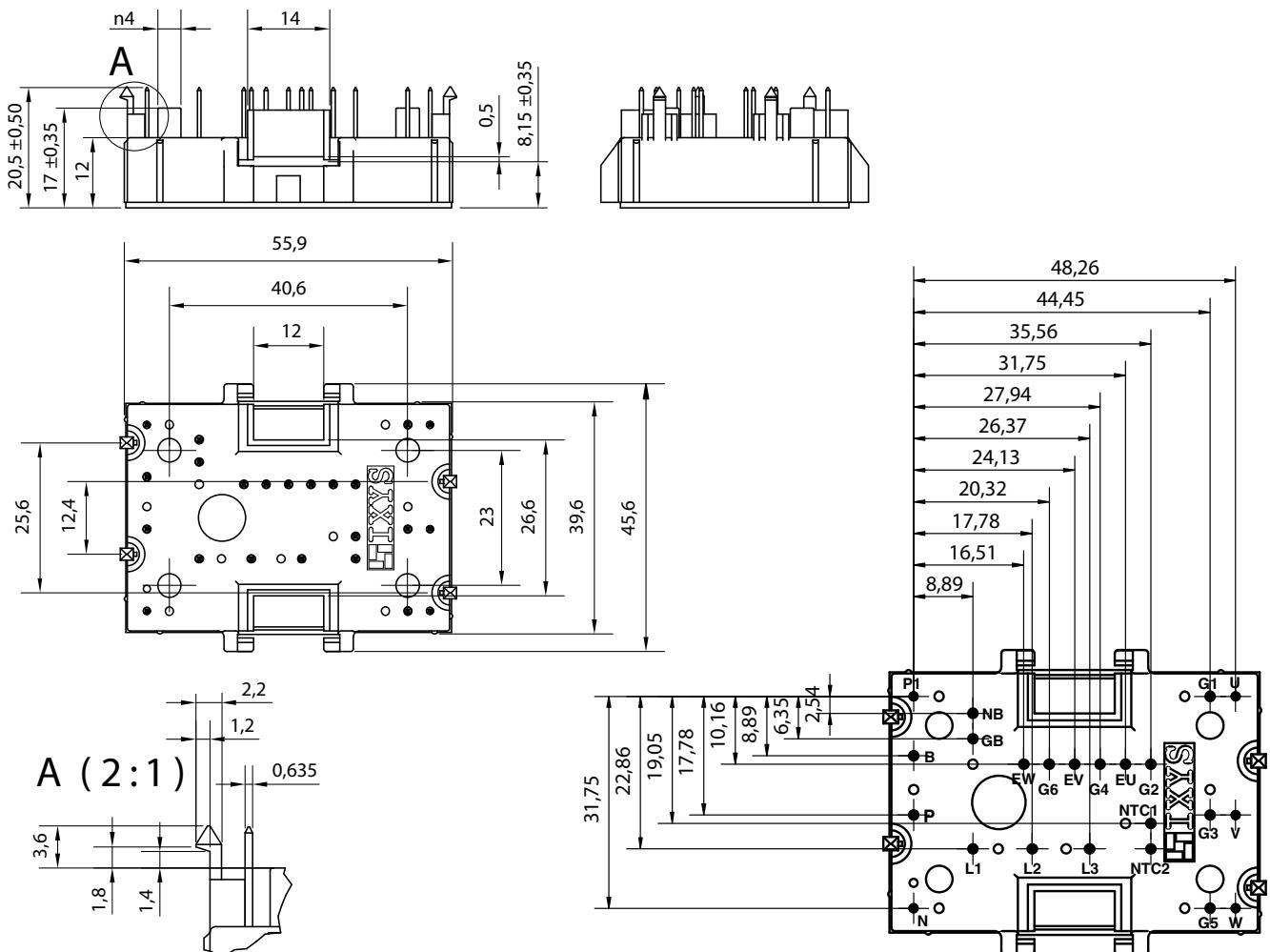
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{25}$	$T = 25^\circ\text{C}$	4.75	5.0	5.25
$B_{25/50}$			3375	k $\Omega$
				K

**Module**

Symbol	Conditions	Maximum Ratings		
		min.	typ.	max.
$T_{VJ}$	Operating	-40...+125		°C
$T_{VJM}$		150		°C
$T_{stg}$		-40...+125		°C
$V_{ISOL}$	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500		V~
$F_c$	Mounting force	40...80		N

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$d_s$	Creepage distance (towards heatsink)	12.7		mm
$d_A$		12		mm
<b>Weight</b>		35		g

Dimensions in mm (1 mm = 0.0394")



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