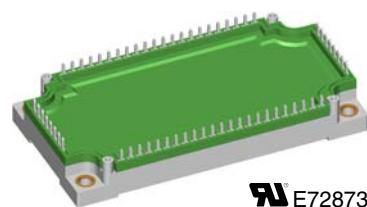
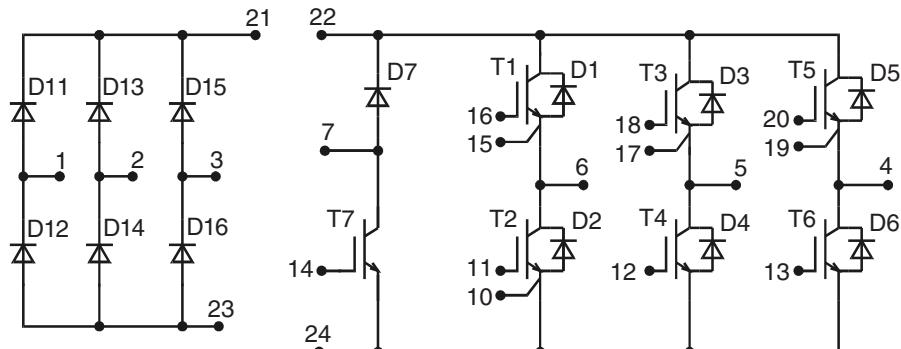


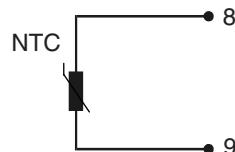
Converter - Brake - Inverter Module (CBI3)



E72873

See outline drawing for pin arrangement

Preliminary data



| Three Phase Rectifier | Brake Chopper | Three Phase Inverter |
|----------------------------|-------------------------------|-------------------------------|
| $V_{RRM} = 1600 \text{ V}$ | $V_{CES} = 600 \text{ V}$ | $V_{CES} = 600 \text{ V}$ |
| $I_{FAV} = 70 \text{ A}$ | $I_{C25} = 50 \text{ A}$ | $I_{C25} = 100 \text{ A}$ |
| $I_{FSM} = 700 \text{ A}$ | $V_{CE(sat)} = 2.0 \text{ V}$ | $V_{CE(sat)} = 2.0 \text{ V}$ |

Input Rectifier D11 - D16

| Symbol | Conditions | Maximum Ratings | | |
|------------|--|-----------------|--|---|
| V_{RRM} | | 1600 | | V |
| I_{FAV} | $T_c = 80^\circ\text{C}$; sine 180° | 50 | | A |
| I_{DAVM} | $T_c = 80^\circ\text{C}$; rectangular; $d = 1/3$; bridge | 140 | | A |
| I_{FSM} | $T_{VJ} = 25^\circ\text{C}$; $t = 10 \text{ ms}$; sine 50 Hz | 700 | | A |
| P_{tot} | $T_c = 25^\circ\text{C}$ | 135 | | W |

Application: AC motor drives with

- € Input from single or three phase grid
- € Three phase synchronous or asynchronous motor
- € Electric braking operation

Features

- € High level of integration - only one power semiconductor module required for the whole drive
- € NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- € Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- € Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- € Temperature sense included

| Symbol | Conditions | Characteristic Values | | |
|------------|--|---|------|-----|
| | | ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified) | | |
| V_F | $I_F = 75 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 1.2 | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 0.8 | mA |
| R_{thJC} | (per diode) | | 0.94 | K/W |

Output Inverter T1 - T6

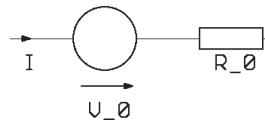
| Symbol | Conditions | Maximum Ratings | | |
|----------------------------|--|-----------------|---------------|---|
| V_{CES} | $T_{VJ} = 25^\circ\text{C}$ to 150°C | 600 | | V |
| V_{GES} | Continuous | ± 20 | | V |
| I_{C25} | $T_C = 25^\circ\text{C}$ | 100 | | A |
| I_{C80} | $T_C = 80^\circ\text{C}$ | 65 | | A |
| RBSOA | $V_{GE} = \pm 15\text{ V}$; $R_G = 15\text{ }\Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100\text{ }\mu\text{H}$ | $I_{CM} = 150$ | | A |
| t_{sc} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15\text{ V}$; $R_G = 15\text{ }\Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive | 10 | μs | |
| P_{tot} | $T_C = 25^\circ\text{C}$ | 320 | | W |

| Symbol | Conditions | Characteristic Values | | |
|---------------|--|---|------|------|
| | | ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified) | min. | typ. |
| $V_{CE(sat)}$ | $I_C = 75\text{ A}$; $V_{GE} = 15\text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 2.0 | 2.5 |
| | | | 2.3 | V |
| $V_{GE(th)}$ | $I_C = 1.5\text{ mA}$; $V_{GE} = V_{CE}$ | 4.5 | | 6.5 |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | | 1.4 | mA |
| | | | 1.5 | |
| I_{GES} | $V_{CE} = 0\text{ V}$; $V_{GE} = \pm 20\text{ V}$ | | 200 | nA |
| $t_{d(on)}$ | Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 300\text{ V}$; $I_C = 75\text{ A}$ $V_{GE} = \pm 15\text{ V}$; $R_G = 15\text{ }\Omega$ | 150 | | ns |
| t_r | | 60 | | ns |
| $t_{d(off)}$ | | 450 | | ns |
| t_f | | 40 | | ns |
| E_{on} | | 4.0 | | mJ |
| E_{off} | | 3.3 | | mJ |
| C_{ies} | $V_{CE} = 25\text{ V}$; $V_{GE} = 0\text{ V}$; $f = 1\text{ MHz}$ | 4.2 | | nF |
| Q_{Gon} | $V_{CE} = 300\text{ V}$; $V_{GE} = 15\text{ V}$; $I_C = 100\text{ A}$ | 260 | | nC |
| R_{thJC} | (per IGBT) | | 0.39 | K/W |

Output Inverter D1 - D6

| Symbol | Conditions | Maximum Ratings | | |
|-----------|--------------------------|-----------------|--|---|
| I_{F25} | $T_C = 25^\circ\text{C}$ | 140 | | A |
| I_{F80} | $T_C = 80^\circ\text{C}$ | 85 | | A |

| Symbol | Conditions | Characteristic Values | | |
|------------|--|-----------------------|------|------|
| | | min. | typ. | max. |
| V_F | $I_F = 75\text{ A}$; $V_{GE} = 0\text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$ | 1.7 | 2.0 | V |
| | | 1.2 | | V |
| t_{rr} | $I_F = 60\text{ A}$; $dI_F/dt = -500\text{ A}/\mu\text{s}$; $T_{VJ} = 125^\circ\text{C}$ $V_R = 300\text{ V}$; $V_{GE} = 0\text{ V}$ | 28 | | A |
| | | 100 | | ns |
| R_{thJC} | (per diode) | | 0.61 | K/W |

Equivalent Circuits for Simulation**Conduction**

IGBT (typ. at $V_{GE} = 15\text{ V}$; $T_J = 125^\circ\text{C}$)
T1-T6

$$V_0 = 1.21\text{ V}; R_0 = 15\text{ m}\Omega$$

T7

$$V_0 = 1.06\text{ V}; R_0 = 36\text{ m}\Omega$$

Diode (typ. at $T_J = 125^\circ\text{C}$)

D1-D6

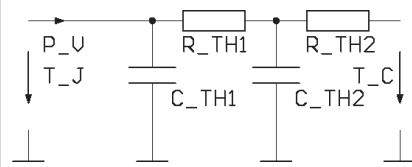
$$V_0 = 1.1\text{ V}; R_0 = 2\text{ m}\Omega$$

D7

$$V_0 = 1.1\text{ V}; R_0 = 12\text{ m}\Omega$$

D11-D16

$$V_0 = 0.85\text{ V}; R_0 = 5\text{ m}\Omega$$

Thermal Response

IGBT (typ.)

T1-T6

$$C_{th1} = 0.177\text{ J/K}; R_{th1} = 0.293\text{ K/W}$$

$$C_{th2} = 1.228\text{ J/K}; R_{th2} = 0.097\text{ K/W}$$

T7

$$C_{th1} = 0.088\text{ J/K}; R_{th1} = 0.583\text{ K/W}$$

$$C_{th2} = 0.799\text{ J/K}; R_{th2} = 0.167\text{ K/W}$$

Diode (typ.)

D1-D6

$$C_{th1} = 0.138\text{ J/K}; R_{th1} = 0.48\text{ K/W}$$

$$C_{th2} = 0.957\text{ J/K}; R_{th2} = 0.13\text{ K/W}$$

D7

$$C_{th1} = 0.038\text{ J/K}; R_{th1} = 1.725\text{ K/W}$$

$$C_{th2} = 0.439\text{ J/K}; R_{th2} = 0.375\text{ K/W}$$

D11-D16

$$C_{th1} = 0.086\text{ J/K}; R_{th1} = 0.738\text{ K/W}$$

$$C_{th2} = 0.621\text{ J/K}; R_{th2} = 0.202\text{ K/W}$$

Brake Chopper T7

| Symbol | Conditions | Maximum Ratings | | |
|-----------------------------------|---|---|--|---------|
| V_{CES} | $T_{VJ} = 25^\circ C$ to $150^\circ C$ | 600 | | V |
| V_{GES} | Continuous | ± 20 | | V |
| I_{C25} | $T_C = 25^\circ C$ | 50 | | A |
| I_{C80} | $T_C = 80^\circ C$ | 35 | | A |
| RBSOA | $V_{GE} = \pm 15 V$; $R_G = 33 \Omega$; $T_{VJ} = 125^\circ C$ Clamped inductive load; $L = 100 \mu H$ | $I_{CM} = 60$ $V_{CEK} \leq V_{CES}$ | | A |
| t_{sc} (SCSOA) | $V_{CE} = V_{CES}$; $V_{GE} = \pm 15 V$; $R_G = 33 \Omega$; $T_{VJ} = 125^\circ C$ non-repetitive | 10 | | μs |
| P_{tot} | $T_C = 25^\circ C$ | 165 | | W |

| Symbol | Conditions | Characteristic Values | | |
|--|--|---|------|----------------------------------|
| | | ($T_{VJ} = 25^\circ C$, unless otherwise specified) | | |
| | | min. | typ. | max. |
| $V_{CE(sat)}$ | $I_C = 35 A$; $V_{GE} = 15 V$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | 2.0 2.3 | 2.5 | V |
| $V_{GE(th)}$ | $I_C = 0.7 mA$; $V_{GE} = V_{CE}$ | 4.5 | | V |
| I_{CES} | $V_{CE} = V_{CES}$; $V_{GE} = 0 V$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 0.3 | mA |
| I_{GES} | $V_{CE} = 0 V$; $V_{GE} = \pm 20 V$ | | 200 | nA |
| $t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off} | Inductive load, $T_{VJ} = 125^\circ C$ $V_{CE} = 300 V$; $I_C = 35 A$ $V_{GE} = \pm 15 V$; $R_G = 33 \Omega$ | 50 50 270 40 1.63 1.17 | | ns ns ns ns mJ mJ |
| C_{ies} Q_{Gon} | $V_{CE} = 25 V$; $V_{GE} = 0 V$; $f = 1 MHz$ $V_{CE} = 300 V$; $V_{GE} = 15 V$; $I_C = 25 A$ | 1.6 94 | | nF nC |
| R_{thJC} | | | 0.75 | K/W |

Brake Chopper D7

| Symbol | Conditions | Maximum Ratings | | |
|----------------------|---|-----------------------|------|---------|
| V_{RRM} | $T_{VJ} = 25^\circ C$ to $150^\circ C$ | 600 | | V |
| I_{F25} | $T_C = 25^\circ C$ | 35 | | A |
| I_{F80} | $T_C = 80^\circ C$ | 24 | | A |
| Symbol | Conditions | Characteristic Values | | |
| | | min. | typ. | max. |
| V_F | $I_F = 35 A$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | 2.0 1.5 | 2.3 | V |
| I_R | $V_R = V_{RRM}$; $T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$ | | 0.1 | mA |
| I_{RM} t_{rr} | $I_F = 15 A$; $dI_F/dt = -400 A/\mu s$; $T_{VJ} = 125^\circ C$ $V_R = 300 V$ | 13 90 | | A ns |
| R_{thJC} | | | 2.1 | K/W |

IXYS reserves the right to change limits, test conditions and dimensions.

20070912a

Temperature Sensor NTC

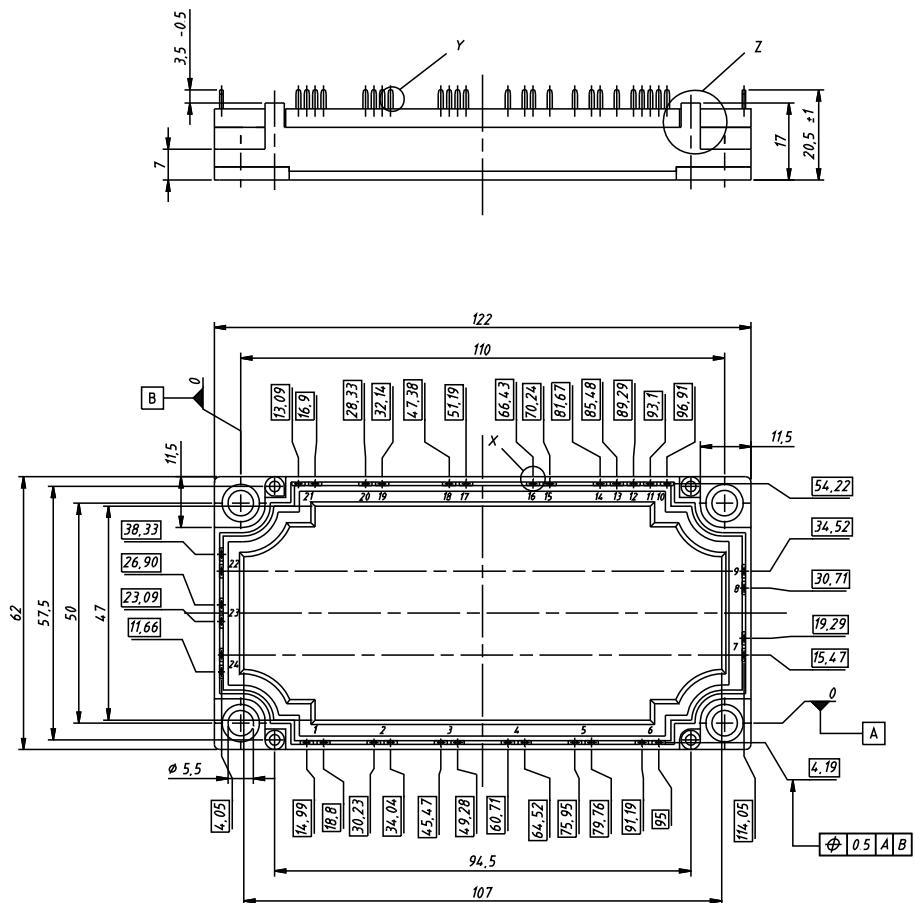
| Symbol | Conditions | Characteristic Values | | |
|-------------|------------------------|-----------------------|------|-----------------|
| | | min. | typ. | max. |
| R_{25} | $T = 25^\circ\text{C}$ | 4.75 | 5.0 | 5.25 k Ω |
| $B_{25/50}$ | | | 3375 | K |

Module

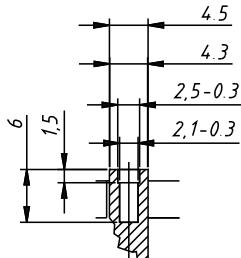
| Symbol | Conditions | Maximum Ratings | | |
|------------|--|-----------------|----|--|
| T_{VJ} | operating | -40...+125 | °C | |
| T_{JM} | | +150 | °C | |
| T_{stg} | | -40...+125 | °C | |
| V_{ISOL} | $I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$ | 2500 | V~ | |
| M_d | Mounting torque (M5) | 3 - 6 | Nm | |

| Symbol | Conditions | Characteristic Values | | |
|----------------|------------------------------|-----------------------|------|------------|
| | | min. | typ. | max. |
| $R_{pin-chip}$ | | | 5 | m Ω |
| d_s | Creepage distance on surface | 6 | | mm |
| d_A | Strike distance in air | 6 | | mm |
| R_{thCH} | with heatsink compound | 0.01 | | K/W |
| Weight | | 300 | | g |

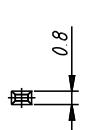
Dimensions in mm (1 mm = 0.0394")



Detail Z



Detail X



Detail Y

